

Full title

1 Section title

The energy functional in general orthogonal curvilinear coordinates (ξ, η) with respective scale factors h_ξ , h_η and Jacobian $J = h_\xi h_\eta$ is

$$\Upsilon(u) = \int_{\Omega} \left(\gamma \|\mathbf{n}\| + \frac{1}{2} \Delta \rho g u^2 + \lambda u \right) d\Omega, \quad (1)$$

where $u(\xi, \eta)$ is the surface, \mathbf{n} is the normal to the function $F = z - u(\xi, \eta)$, the Jacobian J is contained in the differential $d\Omega$, and the rest of the quantities are as in the typical surface tension problem. Introduce a variation $u_\varepsilon = u + \varepsilon v$, $|\varepsilon| \ll 1$ with v vanishing on $\partial\Omega$ with the aim to calculate $\left. \frac{d}{d\varepsilon} \Upsilon(u_\varepsilon) \right|_{\varepsilon=0} = 0$. Express

the normal as $\mathbf{n} = (-\nabla u \cdot \mathbf{1})^T$, where $\nabla u = (u_\xi/h_\xi \quad u_\eta/h_\eta)$. Then

$$\left. \frac{d\|\mathbf{n}\|}{d\varepsilon} \right|_{\varepsilon=0} = \left. \frac{d}{d\varepsilon} \left(1 + \nabla(u + \varepsilon v) \cdot \nabla(u + \varepsilon v) \right)^{1/2} \right|_{\varepsilon=0} = \frac{1}{\|\mathbf{n}\|} \left\{ \frac{u_\xi + \varepsilon v_\xi}{h_\xi} \frac{v_\xi}{h_\xi} + \frac{u_\eta + \varepsilon v_\eta}{h_\eta} \frac{v_\eta}{h_\eta} \right\} \bigg|_{\varepsilon=0} = \frac{\nabla u \cdot \nabla v}{\|\mathbf{n}\|}. \quad (2a)$$

Taking $\mathbf{f} = \nabla u / \|\mathbf{n}\|$ in the following form of the divergence theorem for an arbitrary differentiable vector function \mathbf{f} and scalar differentiable function v

$$\int_{\Omega} \mathbf{f} \cdot \nabla v \, d\Omega = \oint_{\partial\Omega} v (\mathbf{f} \cdot d\mathbf{s}) - \int_{\Omega} v \nabla \cdot \mathbf{f} \, d\Omega \quad (2b)$$

and bearing in mind that $v \equiv 0$ on $\partial\Omega$ results in

$$\int_{\Omega} \frac{\nabla u \cdot \nabla v}{\|\mathbf{n}\|} \, d\Omega = - \int_{\Omega} v \nabla \cdot \left(\frac{\nabla u}{\|\mathbf{n}\|} \right) \, d\Omega. \quad (2c)$$

Then

$$\left. \frac{d}{d\varepsilon} \Upsilon(u_\varepsilon) \right|_{\varepsilon=0} = \int_{\Omega} v \left\{ \frac{\Delta \rho g u + \lambda}{\gamma} - \nabla \cdot \left(\frac{\nabla u}{\|\mathbf{n}\|} \right) \right\} \, d\Omega = 0, \quad (2d)$$

and the expression within the curly braces is the Euler-Lagrange equation.

1.1 Subsection title

The parabolic coordinates are defined by

$$x = \xi\eta, \quad y = \frac{1}{2}(\eta^2 - \xi^2). \quad (3)$$

The constant ξ curves are upward parabolae $y = \frac{1}{2}(x^2/\xi^2 - \xi^2)$ with focus at the origin and directrix $y = -\xi^2$. The constant η curves are downward parabolae $y = \frac{1}{2}(\eta^2 - x^2/\eta^2)$ with focus at the origin and directrix $y = \eta^2$. Figure 1 shows the mesh. The interesting feature about this system is that it allows several distinct types of domain shape. When the domain is defined by $\{(\xi, \eta) \mid 0 \leq \xi \leq \xi_{\text{ex}}, 0 \leq \eta \leq \eta_{\text{ex}}\}$, it is eye-shaped (strictly speaking only the right half, the left is obtained by reflexion or $-\xi_{\text{ex}} \leq \xi \leq \xi_{\text{ex}}$), asymmetric if $\xi_{\text{ex}} \neq \eta_{\text{ex}}$. When $\{(\xi, \eta) \mid 0 < \xi_{\text{in}} \leq \xi \leq \xi_{\text{ex}}, 0 < \eta_{\text{in}} \leq \eta \leq \eta_{\text{ex}}\}$, the domain is of the shape shown by the curved coloured diamond. Of course, its boundaries can be extended along any of the parabolae.

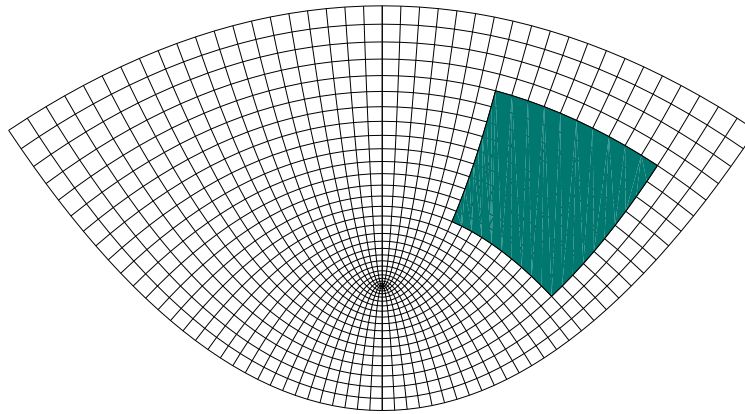


Figure 1: Parabolic coordinates: mesh and domain shape

1.1.1 Subsubsection title

The Octave code to create figure 1 is as follows.

```
clear all
figure(1); clf

xi=-2:0.1:2; lxi=length(xi);
eta=(0:0.1:3)'; leta=length(eta);
Xi=repmat(xi,leta,1);
Eta=repmat(eta,1,lxi);

X=Xi.*Eta;
Y=(Eta.^2-Xi.^2)/2;

h=plot(X,Y,X',Y');
set(h,'color',[0 0 0])
hold on

i=17:27;
j=8:18;
x=[X(i,j(1)); X(i(end),j)'; flipud(X(i,j(end))); flipud(X(i(1),j))'];
y=[Y(i,j(1)); Y(i(end),j)'; flipud(Y(i,j(end))); flipud(Y(i(1),j))'];
p1=patch(x,y,'k');
set(p1,'facecolor',[0 0.47 0.44])

axis equal
```