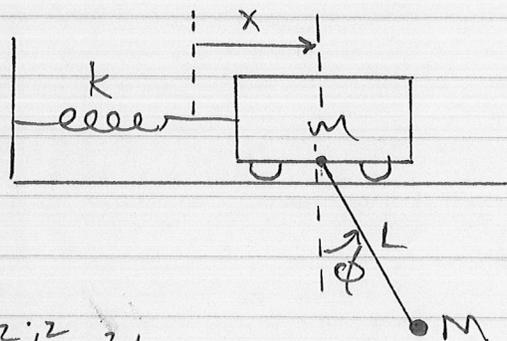


7.31

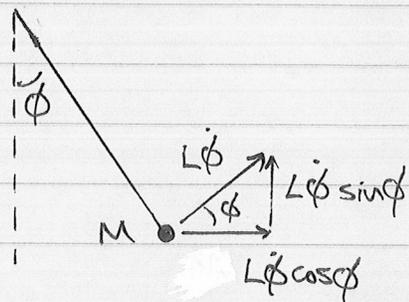
$$a) T = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} M \left[ (\dot{x} + L\dot{\phi} \cos\phi)^2 + (L\dot{\phi} \sin\phi)^2 \right]$$



$$= \frac{1}{2} m \dot{x}^2 + \frac{1}{2} M \left[ \dot{x}^2 + 2L\dot{x}\dot{\phi} \cos\phi + L^2\dot{\phi}^2 \cos^2\phi + L^2\dot{\phi}^2 \sin^2\phi \right]$$

$$= \frac{1}{2} m \dot{x}^2 + \frac{1}{2} M \left[ \dot{x}^2 + 2L\dot{x}\dot{\phi} \cos\phi + L^2\dot{\phi}^2 \right]$$

$$U = \frac{1}{2} k x^2 - MgL \cos\phi$$



$$\rightarrow L = T - U$$

$$= \frac{1}{2} m \dot{x}^2 + \frac{1}{2} M \left[ \dot{x}^2 + 2L\dot{x}\dot{\phi} \cos\phi + L^2\dot{\phi}^2 \right] - \frac{1}{2} k x^2 + MgL \cos\phi$$

Equations of motion:

$$\frac{\partial L}{\partial x} = \frac{d}{dt} \frac{\partial L}{\partial \dot{x}} \rightarrow -kx = \frac{d}{dt} \left[ (m+M)\dot{x} + L\dot{\phi} \cos\phi \right]$$

$$\rightarrow -kx = (m+M)\ddot{x} + L\ddot{\phi} \cos\phi - L\dot{\phi}^2 \sin\phi \quad (1)$$

$$\frac{\partial L}{\partial \phi} = \frac{d}{dt} \frac{\partial L}{\partial \dot{\phi}} \rightarrow -ML\dot{x}\dot{\phi} \sin\phi - MgL \sin\phi = \frac{d}{dt} \left[ ML\dot{x} \cos\phi + ML^2\dot{\phi} \right]$$

$$\rightarrow -ML(\dot{x}\dot{\phi} + g) \sin\phi = ML\ddot{x} \cos\phi - ML\dot{x}\dot{\phi} \sin\phi + ML^2\ddot{\phi} \quad (2)$$

$$(1) \rightarrow (m+M)\ddot{x} + L\ddot{\phi} \cos\phi = L\dot{\phi}^2 \sin\phi - kx$$

$$(2) \rightarrow \ddot{x} \cos\phi + L\ddot{\phi} = \cancel{\dot{x}\dot{\phi} \sin\phi} - \cancel{\dot{x}\dot{\phi} \sin\phi} - g \sin\phi$$

So the eqs. of motion are:

$$\begin{cases} (m+M)\ddot{x} + L\ddot{\phi} \cos\phi = L\dot{\phi}^2 \sin\phi - kx \\ \ddot{x} \cos\phi + L\ddot{\phi} = -g \sin\phi \end{cases}$$

b) if both  $x$  and  $\phi$  are small:

$$\sin\phi = \phi - \frac{\phi^3}{3!} + \dots \approx \phi$$

$$\cos\phi = 1 - \frac{\phi^2}{2} + \dots \approx 1$$

$$\begin{cases} (m+M)\ddot{x} + L\ddot{\phi} = L\dot{\phi}^2 - kx \\ \ddot{x} + L\ddot{\phi} = -g\phi \end{cases} \quad \begin{matrix} \underbrace{\hspace{1cm}} \\ \text{negligible for small } \phi, \dot{\phi} \end{matrix}$$

$$\rightarrow \begin{cases} (m+M)\ddot{x} + L\ddot{\phi} = -kx \\ \ddot{x} + L\ddot{\phi} = -g\phi \end{cases}$$